

# **User Guide**

#### **Product Introduction**

The vibration sensor adopts the original imported sensor, built-in 5 batteries, can be continuously measured, stable data, high precision, strong anti-interference ability, long service life.

#### **Use Case Scenarios**

Suitable for environmental equipment rooms, airports, railway stations, commercial building control, family homes, office buildings, schools, conference rooms, shopping malls, hotels, gymnasiums, cinemas, libraries and other places.



#### **Features**

- 1. Real-time monitoring of vibration values.
- 2. Suspension or stick-on mounting for ease of use.

### **Product Specifications**

| Specifications Specification Specification Specific |  |  |  |  |  |
|--|--|--|--|--|--|
| Model  | UB-VS-N1   |  |  |  |  |
| Power Supply   | 3 *AA batteries (4.5V)   |  |  |  |  |
| Max Current  | 306mA  |  |  |  |  |
| Measuring Range  | Maximum vibration value: 0~1000                                      |  |  |  |  |
| Working Environment  | -40~60°C, 0~80%RH  |  |  |  |  |
| Connector  | Audio  |  |  |  |  |
| Cable Length   | 3m   |  |  |  |  |
| Communication Protocol   | RS485 Modbus RTU Protocol  |  |  |  |  |
| RS485 Address  | 0x41   |  |  |  |  |
| Baud Rate  | 1200 bit/s,2400 bit/s, 4800 bit/s, 9600 bit/s (default), 19200 bit/s |  |  |  |  |

## **Wiring Instruction**



## **Communication protocols**

### 1. Communication basic parameters

| Communication Basic Parameter |              |  |  |  |
|-------------------------------|--------------|--|--|--|
| Coding System                 | 8-bit binary |  |  |  |
| Data Bit                      | 8 bits       |  |  |  |
| Parity Checking Bit           | none         |  |  |  |
| Stop Bit                      | 1 bit        |  |  |  |

| Error Checking | CRC Check   |
|----------------|---|
| Baud Rate      | 1200 bit/s, 2400 bit/s, 4800 bit/s, 9600 bit/s (default), 19200 bit/s |

### 2. Data Frame Format

The Modbus-RTU communication protocol is used in the following format:

■ Initial structure  $\geq$  4 bytes in time.

■ Address code: 1 byte, default 0x41.

■ Function code: 1 byte, support function code 0x03 (read only) and 0x06 (read/write).

■ Data area: N bytes, 16-bit data, high byte comes first.

■ Error check: 16-bit CRC code.

■ End structure  $\geq$  4 bytes of time.

| Request       |               |          |        |             |                 |       |       |       |         |
|---------------|---------------|----------|--------|-------------|-----------------|-------|-------|-------|---------|
| Slave Addres  | s Function (  | Code     | Regist | ter Address | No. of Register | rs CF | C LSB |       | CRC MSB |
| 1 byte        | 1 byte        | 9        | 2      | bytes       | 2 bytes         | 1     | byte  |       | 1 byte  |
| Response      |               |          |        |             |                 |       |       |       |         |
| Slave Address | Function Code | No. of I | Bytes  | Content 1   | Content 1       | •••   | Conte | ent n | CRC     |
| 1 byte        | 1 byte        | 1 by     | rte    | 2 bytes     | 2 bytes         |       | 2 by  | tes   | 2 bytes |

# 3. Register Address

| Register Address |  |                 |               |                                       |  |
|------------------|--|-----------------|---------------|---------------------------------------|--|
| Address (hex)    | Content  | Register Length | Function Code | Description of definitions            |  |
| 0x0000           | Battery Voltage  | 1               | 03            | Unsigned integer data, divided by 100 |  |
| 0x0001           | Cumulative activity time in cycle  | 1               | 03            | Integer                               |  |
| 0x0002           | Maximum vibration value during the cycle (default cycle 60s)   | 1               | 03            | Integer                               |  |
| 0x0003           | Cumulative vibration value<br>during the cycle (default<br>period 60s)                               | 1               | 03            | Integer                               |  |
| 0x0004           | Accumulated activity time during runtime (cleared after each acquisition)                            | 2               | 03            | Integer                               |  |
| 0x0006           | Maximum vibration value during cumulative runtime (cleared for re-collection after each acquisition) | 2               | 03            | Integer                               |  |
| 0x0008           | Total vibration value during cumulative runtime (cleared after each acquisition)                     | 2               | 03            | Integer                               |  |
| 0x000A           | Accumulated runtime in s (clear to re-collect the time after each acquisition)                       | 2               | 03            | Integer                               |  |

| 0x000C | Activity time during cumulative runtime   | 2 | 03    | Integer   |
|--------|---|---|-------|---|
| 0x000E | Maximum vibration value during cumulative runtime (emptied and re-collected after each acquisition) | 2 | 03    | Integer   |
| 0x0010 | Total vibration value during cumulative runtime (cleared after each acquisition)                    | 2 | 03    | Integer   |
| 0x0012 | Accumulated runtime   | 2 | 03    | Integer   |
| 0x0014 | X-axis acceleration   | 1 | 03    | Signed integer  |
| 0x0015 | Y-axis acceleration   | 1 | 03    | Signed integer  |
| 0x0016 | Z-axis acceleration   | 1 | 03    | Signed integer  |
| 0x0017 | Total acceleration  | 1 | 03    | Signed integer  |
| 0x0064 | Address   | 1 | 03/06 | 1 ~ 255   |
| 0x0065 | Baud Rate   | 1 | 03/06 | 1: 4800, 2: 9600, 3:14400, 4:<br>19200, 5: 38400, 6: 115200 |

# **NOTE**

- 1. Do not pull the sensor lead wire, do not drop or hit the sensor violently.
- 2. Do not expose the sensor to high temperatures or long term exposure to steam, water mist, water curtains or condensation..